

1 **Integrated convolutional neural network for skin cancer classification by hair and**
2 **noise restoration**

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Abstract

Background/Aim: Skin lesions are commonly diagnosed and classified using dermoscopic images. There are many artefacts visible in dermoscopy images, including hair strands, noise, bubbles, blood vessels, poor illumination, and moles. As a result, these artefacts can obscure crucial information about lesions, which limits the ability to diagnose lesions automatically.

Materials and methods: In this work, it is investigated how hair and noise artefacts in lesion images affect classifier performance and how they can be removed to improve diagnostic accuracy. A synthetic dataset created using hair simulation and noise simulation is used in conjunction with the HAM10000 benchmark dataset. Moreover, an integrated Convolutional Neural Network (CNN) has been proposed individually for (i) removing hair artefacts using hair inpainting and classification of refined dehair images called Integrated Hair Removal (IHR), (ii) removing noise artefacts using non-local mean denoising and classification of refined denoised images called Integrated Noise Removal (INR).

Results: Five deep learning models are used for the classification: ResNet50, DenseNet121, ResNet152, VGG16, and VGG19. The proposed IHR-DenseNet121, IHR-ResNet50, and IHR-ResNet152 achieve 2.3%, 1.78%, and 1.89% higher accuracy than DenseNet121, ResNet50, and ResNet152 respectively by removing hairs. The proposed INR-DenseNet121, INR-ResNet50, and INR-VGG19 achieve 1.41%, 2.39%, and 18.4% higher accuracy than DenseNet121, ResNet50, and VGG19 respectively by removing noise.

Conclusion: A significant proportion of pixels within the lesion area are influenced by hair and noise, resulting in reduced classification accuracy. However, the proposed CNNs

1 based on Image Hair Restoration (IHR) and Image Noise Reduction (INR) exhibit notably
2 improved performance when restoring pixels affected by hair and noise. The performance
3 outcomes of this proposed approach surpass those of existing methods.

4 **Keywords:** Dermoscopic images, image hair, image noise, convolutional neural network,
5 image restoration, classification

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1. Introduction

Skin cancer is the most prevalent type of cancer, accounting for millions of fatalities worldwide. Melanoma is the deadliest form of skin cancer, causing 10,000 deaths worldwide [1]. Melanoma incidence has increased rapidly all over the world during the last fifty years [2]. The survival rate is over 95% if detected early and only about 15% for late survival [3]. This huge difference emphasizes the importance of melanoma detection and diagnosis at an early stage because it is treatable at this time. Timely detection helps in reducing mortality rates and hence preserves patient lives. Dermoscopy is an imaging procedure that aids in the analysis of skin lesions [4]. The sub-surface structures of the skin can be visually enhanced, exposing deeper skin lesions [5] and providing higher accuracy than the naked eye assessment. However, manual diagnosis demands an expert dermatologist and also suffers from subjective variation and clinical experience, lowering the patient's life expectancy [6]. As a result, computer-aided diagnosis (CAD) systems have emerged to help improve the efficiency of dermoscopy image analysis [7]. An accurate automatic melanoma diagnostic system is critical to assisting dermatologists in making precise diagnosis decisions and reducing the number of unnecessary biopsies. In the arena of clinical medicine, deep neural networks (DNNs) have made major progress and achieved excellent results in image segmentation and classification tasks [8]. However, accurate recognition of skin lesions from dermoscopic images is challenging owing to the presence of certain artefacts, including hair strands, noise, air bubbles, blood vessels, clinical marks, uneven lighting, etc. Skin lesions may be partly obscured or covered by these artefacts, creating a partial occlusion. This kind of image with a partly obscured region makes the diagnosis of an infected area extremely difficult [9].

1 Many classical techniques have been used in literature for hair and noise removal in
2 dermoscopic images [10-18]. Lee et al. [10] presented the first method to remove thick
3 hairs called Dull Razor and used bilinear interpolation. The PDE-based continuous
4 morphological filter has been used by D H Chung et al. to remove undesirable hairs [11].
5 Curvilinear analysis has been used by Zhou et al. to achieve automatic hair and ruler
6 marking recognition, and the artefact is replaced with a feature-guided exemplar-based
7 inpainting technique [12]. To eliminate features from dark hair, Silveira invented the
8 morphological closing and median filter [13]. Top hat filtering is applied by Xie to
9 eradicate thin and curled hairs followed by PDE base inpainting [14]. Abbas et al. [2011]
10 introduced a hair detection and repairing algorithm by using a derivative of Gaussian
11 method to remove hair and then inpaint using a fast-marching method [15]. Toossi et al.
12 [16] implemented a canny edge detector and morphological operators to segment hairs
13 and ruler markings. Multi-resolution transport inpainting is applied to repair hair.
14 Abuzagheh et al. [17] proposed 84 directional filters to identify and disregard hair in skin
15 lesions. Reda Kasmi et al. offered a new method by using 11×11 median filters to remove
16 thin hairs and a Gabor filter for thick hairs [18]. There are some existing methods for
17 noise removal in images [19-25]. A new method for Gaussian noise removal is proposed
18 using multiscale filter banks [20]. A novel effective noise estimation method is proposed
19 based on singular values of corrupted images [21].

20 A few deep learning methods are available for hair removal and image denoising tasks
21 [26-30]. A CNN is built with a post-processing step using the Savitzky-Golay filter and
22 Fourier Domain Filtering [26]. This method can detect the borders belonging to the hair
23 follicles with an average Dice score of 0.83 ± 0.06 . A FCN8-ResNetC based approach for
24 hair removal and segmentation in dermoscopic images is proposed, the training accuracy

1 obtained is 89.38% for hair removal [27]. Jain et al. [28] proposed a fully convolutional
2 CNN for image denoising. An image denoising and blind inpainting method is proposed
3 to combine sparse coding with pre-trained CNNs, achieving decent results in both tasks
4 [29]. Mao et al. proposed an encoding-decoding framework for image denoising and
5 super-resolution. The method combines convolution and deconvolution layers
6 symmetrically by skip connections, which improves the network's performance [30].
7 The limitations of existing research are 1) The present research works mainly measured
8 the hair detection accuracy and error, completely oblivious to the impact on skin lesion
9 patterns. 2) Despite the availability of several methods for hair and noise removal, none
10 of the works focus on the impact of eliminating these artefacts on the overall performance
11 of a CAD system. It is essential to address the effects of hair lines and image noise on the
12 classification accuracy of dermoscopic images to achieve better results and treatment. A
13 deep learning model is developed for the removal of these artefacts. This model could be
14 built into a complete CAD system for dermoscopic images. In this paper, it is studied how
15 the hair and noise data overall affect the automatic detection of skin lesions. The deep
16 learning model is run with the hair and noise artefacts and compared with ground truth
17 images. An Integrated Convolutional Neural Network (CNN) with image inpainting is
18 proposed to fix unwanted hairs and restore the color and texture of skin pixels below them
19 (called dehairing), termed Integrated Hair Removal (IHR). This network performs image
20 inpainting to eliminate unwanted hair initially and then integrates with deep learning
21 models to perform classification and study the effect of removing hair. Secondly, an
22 Integrated CNN with image denoising is implemented to remove noise from images
23 (called denoising), termed Integrated Noise removal (INR). This integrated CNN first
24 performs image denoising to reduce noise and then integrates with deep learning models

1 to perform classification and study the effect of removing noise. The training and
2 validation results after dehairing and denoising are compared with ground truth images.
3 The results show that the training and validation accuracies improve when hair strands
4 and noise are eliminated. These artefacts removal helps in better pattern analysis of
5 dermoscopy images by de-occluding lesion boundary or texture, hence resulting in
6 accurate classification. The core contributions of the work are:

- 7 • The investigation of the effect of image distortions like hair and noise on the
8 performance of a skin CAD system.
- 9 • Two datasets are created wherein new hairs and noise are added.
- 10 • Integrated CNNs namely IHR and INR are developed to leverage the advantage
11 of removing hair and noise artefacts integrated with deep learning models for the
12 improved classification of skin lesions.
- 13 • The evaluation of the performance of proposed integrated deep learning models
14 against the hairy and noisy dataset through extensive experimentation.
- 15 • Assessing the improved results based on accuracy and loss function when these
16 distortions are removed.

17 The remainder of the paper is structured as: Section 2 covers the dataset used, proposed
18 methodology, architecture, and network training. Section 3 presents the implementation
19 and experimental results. In Section 4 results are discussed to analyze the performance of
20 the proposed work. Section 5 includes the conclusion and future aspects of the work.

21 **2. Materials and Method**

22 **2.1. Dataset Description**

23 The benchmark dataset HAM10000 [31] is considered in this work. This is the ISBI
24 Challenge dataset available as ISIC 2018. It is a collection of 10015 skin lesion images

1 divided into seven categories. The seven classes are melanocytic nevus, basal cell
2 carcinoma, actinic keratosis, melanoma, benign keratosis, dermatofibroma, and vascular
3 lesion.

4 In a real-life scenario, the major artefacts causing factors are hair and noise. Though the
5 images in the dataset are partially occluded by artefacts namely hair, rulers, moles, ink
6 markings, etc. there are very few images causing major occlusion. The major concern in
7 the detection and assessment of lesions is the lack of an appropriate dataset with major
8 artefacts like hair and noise. Therefore, two synthetic datasets are generated called Hair
9 Dataset and Noise Dataset. The hair and noise are introduced in images to obstruct the
10 lesion region. These datasets are created to produce partial occlusion in skin cancer
11 images and contain 5000 images. The images in the Hair Dataset are occluded by adding
12 hair strands. For the Noise Dataset, Gaussian noise [32] is added to create a partial
13 occlusion of the lesion area. For training, 80% of the whole data is taken and for testing
14 20% data is considered. Table 1 shows images in each dataset.

15 **Hair Dataset:** Hair is a major partial occlusion causing element in dermoscopic images
16 of skin. The skin images contain thick and thin hairlines. The 5000 images are chosen
17 from the original HAM10000 dataset. These images chosen contain no hair or very few
18 hairs. Hair is extracted from other dermoscopic images with more hair. This is done to
19 maintain a natural hair artefact appearance. Hair is taken out from hairy images using
20 masking technique and then these hairs are superimposed on selected images for Hair
21 Dataset.

22 **Noise Dataset:** The 5000 images are chosen from the original HAM10000 dataset and
23 noise is added. These images are chosen from the dataset that contains no noise. Low
24 lighting and a scarcity of resources for capturing medical images with clinical equipment

1 result in large noise fluctuations in lesion images. Gaussian noise [32] is opted here as it
2 is a main source of noise in digital photos while acquisition, such as sensor noise brought
3 on by inadequate lighting and transmission noise.

4 A (typically) modest amount will be added or subtracted from each pixel's original value
5 in the image. In dermoscopic images, Gaussian noise is a major noise that can happen
6 during acquisition. All images may contain noise, varying in intensity. Here, Gaussian
7 noise is added with zero mean and scale (σ) varied from 1 to 30. Figure. 1(a-h) shows a
8 few examples of Gaussian Noise added to Noise Dataset.

9 **2.2. Proposed Methodology**

10 The proposed Integrated CNN model is described in this section. The methods employed
11 for hair and noise restoration i.e. IHR and INR are presented. The deep learning models
12 used for dermoscopic images and their classification is discussed.

13 **Convolutional Neural Networks**

14 Convolutional neural networks (CNN) contribute to image and video recognition tasks
15 on a broad scale. There are several advantages to employing CNN over standard neural
16 networks, including the ability to learn spatial hierarchies of patterns. It enables CNN to
17 acquire increasingly complex and abstract visual concepts and analyse images with great
18 efficiency. A vast number of images are necessary to train a new CNN model. This
19 scenario relates to a situation in which the entire network must be trained. In this
20 situation, all the network's parameters must be learned from the ground up. This
21 approach necessitates extremely large datasets, which are frequently unavailable for
22 medical purposes. However, employing a standard network allows for the option of
23 transfer learning.

1 Transfer learning is a technique that uses a model trained on one dataset as the basis for
2 a model trained on another. The model that is already trained is known as a pre-trained
3 model. Typically, these models are built on ImageNet [33], a dataset of over fourteen
4 million images and can classify images into over 1,000 different categories. In addition
5 to using the same architecture as a standard network, one may also use parameters learnt
6 by the CNNs with earlier training on a different dataset. Therefore, to adjust the network
7 for the classification of a new target dataset, there are two possible ways. One way is to
8 replace only the final classification layer according to one's target dataset, i.e., the
9 network can be used to classify new dataset images. In another approach, the parameters
10 gained from the model's training over a large dataset are fine-tuned through transfer
11 learning. This allows the network's early layers to extract highly generalizable patterns
12 from a larger dataset, and the network's later layers will take on the details of the new
13 dataset for the adapted model.

14 In this paper, the first approach is followed i.e., the final classification layer is modified.
15 The proposed CNN for dermoscopic image classification is given in Figure. 2. As a
16 result, the time-consuming training stages are avoided and benefits are gained from the
17 features learnt during the training over many images through transfer learning.

18 The most successful methods submitted for ISIC challenges 2016, 2017, 2018, 2019 and
19 2020 [34] used CNNs pre-trained on the ImageNet [33] database. Five deep transfer
20 learning models used in this work are ResNet50 [35], DenseNet121 [36], ResNet152
21 [35], VGG16 [37], and VGG19 [38]. These models are used to find how the system
22 performs in the case of partly occluded image data. Table 2 shows the deep learning
23 architectures used.

24

1 **Integrated CNN with Image Inpainting for Hair Removal (Dehairing)**

2 An integrated CNN with inpainting is proposed for the classification of dermoscopic
3 images shown in Figure. 3. Integration here defines a combination of two methods viz.
4 skin cancer image inpainting and classification. Inpainting is done to restore hairs by
5 substituting them with patches that resemble the nearby pixels. This reduces the impact
6 of hairs on diagnosis analysis. Five deep learning models are applied for the
7 classification of refined skin cancer images. These models are named IHR-ResNet50,
8 IHR-DenseNet121, IHR-ResNet152, IHR-VGG16, and IHR-VGG19. Algorithm 3
9 explains an integrated CNN with inpainting for hair removal. Hair Dataset contains 5000
10 images where new hairs are added (Ref. Section 2.1). Removal of dark, dense hairs and
11 regions that resemble hair is to be done properly as it aids in effective segmentation and
12 classification of features. Numerous techniques are available in the literature for
13 removing hair in dermoscopic images, based on morphological operations [39] and
14 thresholding [40]. Although being fast, these techniques tend to eliminate subtle,
15 significant features that can be mistaken for hair. An effective method for dermoscopic
16 hair removal is the black-hat transform followed by inpainting, which is employed here,
17 and described in Algorithm 2.

18 The first step is to perform the Gaussian blur and median blur operations before applying
19 other methods to reduce the high-frequency data. It removes noise and edges from an
20 image while preserving its original data. Gaussian blur is a low-pass filter that
21 determines the variation to apply to each pixel of the image using a Gaussian function.
22 Its purpose is to smooth down sphere edges, which frequently have inconsistencies
23 because of the marker's rough surface. It is also used to reduce skin lines, air bubbles,
24 light, and small hairs around the lesion. The kernel used is 3×3 and σ is the standard

1 deviation of the Gaussian kernel. The median filter is a nonlinear filter and is very
 2 effective in removing noise while preserving edges. The current pixel value is replaced
 3 with the median value in a 3 x 3 neighborhood.

4 The input dermoscopic image is converted from RGB to grayscale, followed by a
 5 morphological filter to find the hair contours. The morphological filter, called "black
 6 hat," is employed on the grayscale image. It gives a difference between the closing and
 7 the given input image. Closing eliminates the foreground's tiny holes. Black Hat extracts
 8 the dark objects smaller than the structuring element and finally outputs them as bright
 9 spots. An 11×11 cross-shaped structural element is defined. To intensify the hair
 10 contours, a thresholding operation is applied to the output of the black hat filter. This
 11 generates a binary mask. All unrequired objects present in the dermoscopic image are
 12 discarded, and only the hairlines are detected. Following this, an inpainting algorithm,
 13 TELEA [41], given in Algorithm 1, is used to restore the image by removing the hair
 14 structures from it. It preserves the appearance by replacing the hair structures with nearby
 15 pixels, producing a clear dermoscopic image. The eq. (1) shows point p is inpainted as a
 16 function of all points q in $B_{\epsilon}(p)$ by summing the estimates of all points q , weighted by a
 17 normalized weighting function $w(p, q)$,

$$18 \quad I(p) = \frac{\sum_{q \in B_{\epsilon}(p)} w(p, q) [I(q) + \nabla I(q)(p - q)]}{\sum_{q \in B_{\epsilon}(p)} w(p, q)} \quad (1)$$

19 where $I(q)$ is the original image and $I(p)$ is an inpainted image. In algorithm 1, Ω is the
 20 region to be inpainted, $\partial\Omega$ is the boundary of the region to be inpainted and $B_{\epsilon}(p)$ is a
 21 neighborhood of p . To inpaint the whole Ω , apply Equation 1 iteratively to all the pixels
 22 of $\partial\Omega$, in increasing distance from $\partial\Omega$'s initial position $\partial\Omega_i$. Complete the boundary

1 inside Ω until the whole region has been inpainted. Figure. 4 shows the stages of the hair
 2 removal process.

3 **Algorithm 1: INPAINT_TELEA**

4 $\delta\Omega_i$ = boundary of the region to inpaint

5 $\delta\Omega = \delta\Omega_i$

6 while ($\delta\Omega$ not empty)

7 {

8 p = pixel of $\delta\Omega$ closest to $\delta\Omega_i$

9 inpaint p using Eq.1

10 advance $\delta\Omega$ into Ω

11 }

12

13 **Algorithm 2: Dehair_Inpainted (Image, Kernel, Mask)**

14 Input: Image, Kernel, Mask

15 Output: Skin images with Inpainted Hair

16 G_Blur \leftarrow GaussianBlur (Image, Kernel * Kernel, σ)

17 Med_blur \leftarrow MedianBlur (G_Blur, Kernel)

18 Image_GrayScale \leftarrow Color (Med_blur, RGB2GRAY)

19 Kernel1 \leftarrow StructuringElement (Morph_Cross, Kernel)

20 Blackhat \leftarrow MorphologyEx (Image_GrayScale, MORPH_BLACKHAT, Kernel1)

21 ret_v, Thresh2_Image \leftarrow Threshold (Blackhat, Thresh, Thresh_MaxVal,

22 THRESH_BINARY)

23 Output_Image \leftarrow Inpaint (Med_blur, Thresh2_Image, 1, INPAINT_TELEA)

24 Dehair_Inpainted \leftarrow Color (Output_Image, COLOR_BGR2RGB)

25

26 **Algorithm 3: Integrated CNN with Inpainting for Hair Removal**

27 Input: Skin Images from HAM10000

28 Output: Hair removal Inpainted results with Accuracy and Loss

29 1) Input Skin cancer Images M_1, \dots, M_n

- 1 2) For each Image M_i ,
 - 2 do
 - 3 Dehair_Inpainted (M_i , Kernel, Mask)
 - 4 3) For each Dehair_Inpainted image M_i , $\text{resize} = 224*224$
 - 5 4) Fine-tune the last fully connected (FC) layer of deep CNN to identify the
 - 6 probabilities of seven skin cancer classes.
 - 7 5) Train five deep CNNs IHR-ResNet50, IHR-DenseNet121, IHR-ResNet152, IHR-
 - 8 VGG16 and IHR-VGG19.
 - 9 6) Validate the model and calculate training and validation accuracy and loss for
 - 10 performance evaluation.
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11

12 **Integrated CNN with Image Denoising for Noise Removal (Denoising)**

13 An integrated CNN with noise removal is proposed for the classification of dermoscopic
14 images shown in Figure. 5. Integration here defines a combination of two methods viz.
15 skin cancer images' noise removal and classification. Denoising is done to take out
16 undesirable noise from images so that they can be better analyzed. Five deep learning
17 models are applied for the classification of refined skin cancer images. These models are
18 named INR-ResNet50, INR-DenseNet121, INR-ResNet152, INR-VGG16, and INR-
19 VGG19. Algorithm 4 explains an integrated CNN with denoising for noise removal.
20 5000 images from the Noise Dataset, in which noise is added are now denoised. The
21 process of reconstructing a signal from noisy images is referred to as denoising an image.
22 Non-local means [42] is utilized as the method of denoising to remove any probable
23 aberrations from the image. The Non-Local (NL) Means Algorithm selects a pixel, draws
24 a small window around it, and searches the image for other windows of the same size. It
25 then performs an average of all the windows and calculates the resultant value for the
26 pixel. The non-local signifies the whole image search, not an individual region. Given a

1 noisy image $v = \{v(i) / i \in I\}$, the $NL[v](i)$, for a pixel i , is computed as a weighted
2 average of all the pixels in the image, given in Eq. (2),

$$3 \quad NL[v](i) = \sum_{j \in I} w(i, j)v(j) \quad (2)$$

4 where $\{w(i, j)\}_j$ depends on the similarity between the pixels i and j . It is used as the
5 OpenCV function: `fastNlMeansDenoisingColored`. The function converts the image to
6 CIELAB color space and then separately denoises the L and AB components with given
7 h parameters using the `FastNon-LocalMeansDenoising` function. Larger search windows
8 require longer denoising times. The ideal value for the luminance and color components
9 is 10, and the higher the value, the smoother the image will be. All the images from the
10 Noise Dataset are run through this process for reconstruction.

11 **Algorithm 4: Integrated CNN with Non-Local Means for Denoising**

12 Input: Skin Images from HAM10000

13 Output: Noise removal results with Accuracy and Loss

- 14 1) Input Skin cancer Images M_1, \dots, M_n
- 15 2) For each Image M_i ,
16 Denoise \leftarrow `fastNlMeansDenoisingColored` (Input_img, Out_Image,
17 Lum_comp, color_comp, template_win, search_win)
- 18 3) For each Denoised image M_i , `resize = 224*224`
- 19 4) Fine-tune the last fully connected (FC) layer of deep CNN to identify the
20 probabilities of skin cancer classes.
- 21 5) Train five deep CNNs INR-ResNet50, INR-DenseNet121, INR-ResNet152, INR-
22 VGG16 and INR-VGG19.
- 23 6) Validate the model and calculate training and validation accuracy and loss for
24 performance evaluation.

25 **2.3. Model Training**

26 Transfer learning is employed for training the IHR and INR models on the dataset,
27 utilizing pre-trained weights obtained through training on the ImageNet dataset. Five pre-

1 trained models are implemented for the given dataset. The model's weights are loaded
2 and the final fully connected layer is removed. The remaining part of the model is used
3 as a feature extractor for the given dataset. A new final fully connected layer is added to
4 get the skin lesion classes required for output which is 7.

5 The network is trained for 25 epochs. Table 1 shows the hyperparameters used to train
6 the model. The input image size for the model is a $224 \times 224 \times 3$ RGB image. ReLU [43]
7 activation function is employed throughout the architecture and the optimization function
8 used is Adam [44]. The loss function applied is categorical cross entropy [45]. Table 3
9 shows all the hyperparameters and their values.

10 **Fully Connected Layer:**

- 11 • There is a need to categorise the data into several classes after feature extraction,
12 which can be achieved with a fully connected (FC) layer.
- 13 • The fully connected layer in the convolutional network takes the outcome of the
14 convolution/pooling process and makes a classification judgement.
- 15 • *Fully Connected Input:* The output of the final Pooling/Convolutional Layer is
16 flattened, turned into a single vector and sent as the input into the fully connected
17 layer.
- 18 • *Fully Connected Output:* It gives the final probabilities for each label.
- 19 • The final layer employs the softmax activation function to determine the
20 likelihood that the input belongs to one of several classes (classification). The
21 class probabilities are calculated and output in a 3D array with $[1 \times 1 \times N]$
22 dimensions, where N is the number of classes.

23

24

1 **ReLU Activation Function:**

- 2 • The rectified linear activation function (ReLU) [43] is a non-linear function and
3 can learn complex relationships from the training data.
- 4 • ReLU is very easy to compute and implement since it just requires a comparison
5 between its input and the value 0.
- 6 • A ReLU function will apply a $\max(0, x)$ function. The function outputs the input
7 directly if it is positive, otherwise, it will output zero.
- 8 • Derivative remains constant i.e. 1 for a positive input and thus reduces the time
9 taken for the model to learn and in minimizing the errors.
- 10 • ReLU has a predictable gradient for the backpropagation of the error. As a
11 consequence, the computation speed is very quick.

12 **Categorical Cross-Entropy Loss:**

- 13 • The network's performance is measured using a metric (loss function) that counts
14 the similarity between predicted and actual value. Cross-entropy loss is the most
15 important cost function used in multi-class classification.
- 16 • The objective of the loss function is to optimize the model during training [45].
17 To optimise the loss function, parameters are modified iteratively and help in
18 correct prediction.
- 19 • The model performs better when loss is low.

20 **3. Experimental Results and Discussion**

21 The implementation of the proposed architecture is done in Google Colab. The
22 classification accuracy and loss of the trained CNN models are calculated for training and
23 validation. ResNet50 [35], DenseNet121 [36], ResNet152 [35], VGG16 [37], and VGG19
24 [38] models are run on ground truth images from HAM10000 Dataset and the

1 corresponding images adulterated by the Hair Dataset and Noise Dataset. The models
2 IHR-ResNet50, IHR-DenseNet121, IHR-ResNet152, IHR-VGG16, and IHR-VGG19 are
3 run on Hair Dataset after dehairing. The models INR-ResNet50, INR-DenseNet121,
4 INR- ResNet152, INR-VGG16, and INR-VGG19 are run on Noise Dataset after
5 denoising the images. All the models are run for 25 epochs. Here, the results are shown
6 after 10, 15, and 25 epochs. The performance metrics used to validate the results are
7 Training Accuracy (TAcc), Training Loss (TLoss), Validation Accuracy (VAcc), and
8 Validation Loss (VLoss).

9 **3.1. Experimental Results on HAM Dataset**

10 Skin cancer images are taken from the Ground Truth (GT) Dataset (HAM). This dataset
11 comprises 10,015 images. All the models are run on these images. Table 4 shows training
12 and validation accuracies on the GT Dataset. Table 5 shows training and validation loss
13 on the GT Dataset.

14 **3.2. Experimental Results with Hair Dataset**

15 The model performance for Hair Dataset is shown in Tables 6-9. Table 6 shows training
16 and validation accuracy on Hair Occluded images. Table 7 shows training and validation
17 loss on Hair Occluded images. DenseNet121 gives a training accuracy of 95.20% with a
18 validation accuracy of 87.10%. VGG19 with occluded hair gives a training accuracy of
19 85.03 and a validation accuracy of 78.62%.

20 **Dehairing results using Proposed Integrated CNN with Hair Inpainting**

21 Dehairing is performed using Algorithm 3 proposed in Section 2.2. Table 8 shows training
22 and validation accuracy after Dehairing. Table 9 shows training and validation loss after
23 Dehairing. It can be seen that training and validation accuracy decreases when the skin
24 image is occluded with hair strands. DenseNet121 gives a training accuracy of 95.20%

1 with hair while IHR-DenseNet121 provides 97.50% accuracy with hair removal. The
2 validation accuracy with Densenet121 is 87.10% when hair is present while 89.16% with
3 IHR-DenseNet121 when hairs are removed. There is an improvement of approximately
4 2% accuracy with IHR-Densenet121. For each model, there is an increase in training and
5 validation loss when the lesion is obstructed with hair.

6 Figure. 6 shows a comparison of improvement in training accuracy and loss after
7 dehairing.

8 The training accuracy and loss curves are drawn and contrasted for both hair and dehair
9 datasets. It is seen that accuracy and loss curves after dehairing with the proposed IHR
10 models are better and show improved results than with hair.

11 **3.3. Experimental Results with Noise Dataset**

12 The model performance for Noise Dataset is shown in Tables 10-13. Table 10 shows
13 training and validation accuracy on Noise Occluded images. Table 11 shows training and
14 validation loss on Noise Occluded images. Dense-Net121 achieves highest training
15 accuracy of 96.04% and validation accuracy of 86.50%. VGG19 with occluded noise
16 gives a training accuracy of 78.25 and a validation accuracy of 76.75%.

17 **Denoising Results using Proposed Integrated CNN with Non-Local means Denoising**

18 Denoising is performed using Algorithm 4 proposed in Section 2.2. Table 12 shows
19 training and validation accuracy after Denoising. Table 13 shows training and validation
20 loss after Denoising. It can be seen that training and validation accuracy decreases when
21 the skin image is distorted with noise. DenseNet121 gives training accuracy of 96.04%
22 with noise and 97.45% with INR-DensetNet121 when noise is removed.

23 The validation accuracy with Densenet121 is 86.50% when noise is present while INR-
24 DenseNet121 gives 87.58% when noise is removed. There is an improvement of

1 approximately 1% in accuracy with INR-Densenet121. For each model, there is an
2 increase in training and validation loss when the lesion is obstructed with noise.

3 Figure. 7 shows a comparison of improvement in training accuracy and loss after
4 denoising. The training accuracy and loss curves are drawn and contrasted for both noise
5 and denoise datasets. It is seen that INR models give more accurate output. The accuracy
6 and loss curves after denoising are better and show improved results than with noise.

7 **3.4. Comparison of Ground Truth with Hair, Noise, Dehairing and Denoising**

8 Extensive experimentation is performed to analyze the distortions' effect on the overall
9 diagnosis of skin lesions. Here, comparison graphs are drawn that compare ground truth
10 results with the occluded dataset (Hair Dataset and Noise Dataset) and refined dataset
11 (dehairing and denoising). Figure. 8 shows a comparison between training and validation
12 accuracy for ground truth, hair and dehair images. Figure. 9 shows a comparison between
13 training and validation loss for ground truth, hair and dehair images.

14 The proposed IHR model is employed for dehairing. Figure. 10 shows a comparison
15 between training and validation accuracy for ground truth, noised, and denoised images.
16 Figure.11 shows a comparison between training and validation loss for ground truth,
17 noised, and denoised images. The proposed INR model is employed for denoising.

18 From Figure. 10-13, it can be interpreted that the proposed IHR-DenseNet121 achieves
19 2.3% higher accuracy than DenseNet121 with hair occlusion and the proposed INR-
20 DenseNet121 achieves 1.41% higher accuracy than DenseNet121 with noise occlusion.

21 It can be interpreted from the results that these appearances often result in low accuracy
22 and high loss in skin lesion classification. The comparison of the results computed by
23 deep learning models with and without artefacts has exposed a significant difference in
24 employing a method for restoring distorted parts.

4. Discussion

4.1. Performance Comparison with Existing Methods

The performance of the proposed hair removal method is compared with published hair detection and segmentation algorithms. Table 14 shows the accuracy metric computed for all algorithms in the presence of hair and after dehairing. The proposed noise removal is compared with available methods for denoising. Table 15 shows the accuracy metric computed for all algorithms after denoising.

Table 14 and Table 15 show that the proposed methods achieve comparable results to existing computer vision techniques. The proposed IHR-DenseNet121, IHR-ResNet50 and IHR-ResNet152 outperform existing methods in dehairing. INR-DenseNet121, INR-ResNet50 and INR-VGG19 models for noise removal beat available methods in the literature. The proposed methods can remove partial occlusion causing elements with more accuracy and perform precise classification of lesions according to class.

In this work, the effects of skin images occluded with hair and noise are analyzed. Components, such as hair and noise, affect image quality and cause classification inaccuracies. These artefacts disrupt the features that get occluded behind them. If a lesion feature is not accurately determined, the diagnosis may not be appropriate. Therefore, it is necessary to diminish the effect of such elements.

This is the first work where 5000 images are adulterated with hair and noise. The projected model can successfully eliminate the effects of occluded regions thereby resulting in better precision. Skin lesions bounded by these undesirable artefacts such as hair and noise are successfully corrected and classified with the inclusion of IHR and INR models with Inpainting and Non-Local Means, respectively. These methods mask any hair and noise hiding the lesion part and preserve the features occluded by them. The

1 examination of results after applying these methods has shown that the integrated models
2 are capable of effectively classifying skin lesions regardless of the presence of unwanted
3 artefacts. This automatic and efficient CAD system can help in the robust analysis of skin
4 lesions in dermoscopic images saving doctors and patients' time.

5 **5. Conclusion**

6 Skin lesion images suffer from artefacts like hairy pixels, noise, poor color contrast, low
7 illumination, moles, bubbles, resolution, etc. In this work, datasets are created with hair
8 and noise to make this CAD system fit in a more realistic scenario. The hairy strands in
9 skin lesion images add extra features that can lead to misdiagnosis. Noise artefacts
10 diminish the visual quality of digital images, lowering the precision and accuracy of
11 image analysis operations. The effect of noise and hair artefacts on diagnostic accuracies
12 is studied here and it is perceived that these artefacts lack accuracy and can be a reason
13 for inaccurate analysis. Noise and hair removal techniques can enhance image quality.
14 Removal and restoration of the regions after hair and noise removal is vital so that features
15 within lesions can be examined more thoroughly and primary stage. It is concluded that
16 the proposed integrated CNN i.e. IHR and INR can do an improved and accurate
17 diagnosis of lesions from dermoscopic images after image restoration. This analysis is
18 crucial to studying unwanted segmentation and classification results of lesion images due
19 to the presence of the hairs and noise covering them. The output of the proposed methods
20 delivers more accurate and quality results. Many other artefacts like ruler marks, color
21 charts, ink marks, moles, a fuzzy border, and numerous shades of color should also be
22 isolated and corrected. There is a necessity for an automatic hair removal method that
23 preserves all the lesion features in the presence of all these artefacts while keeping its
24 computational cost low for accurate melanoma recognition and classification tasks. The

1 future work focuses on developing a deep learning method for image inpainting and
2 restoration.

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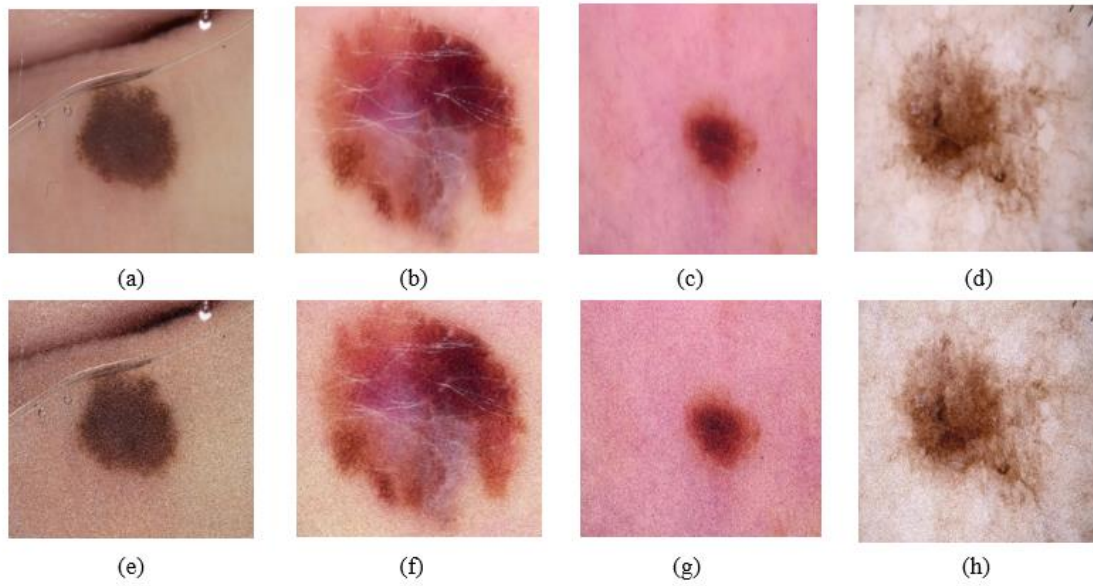
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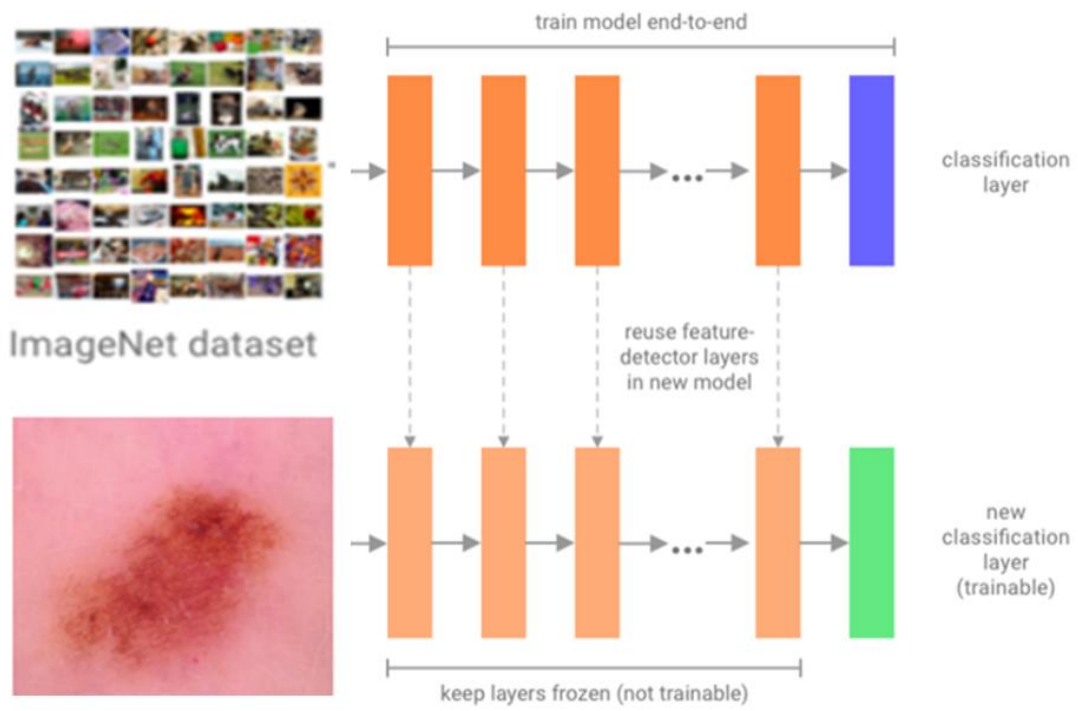
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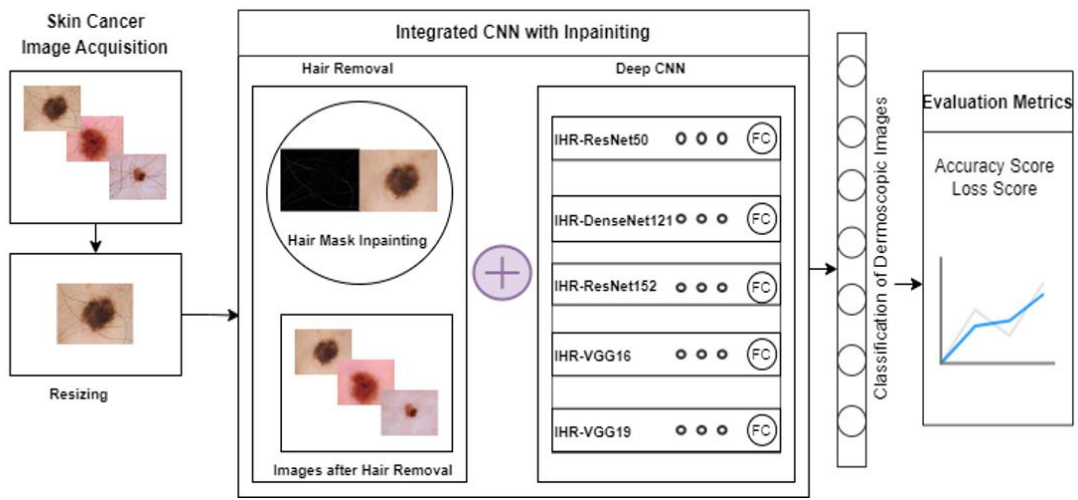
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1
2 **Figure. 1** (a)-(d) are images from original HAM10000 dataset, (e)-(h) are
3 corresponding noise added images

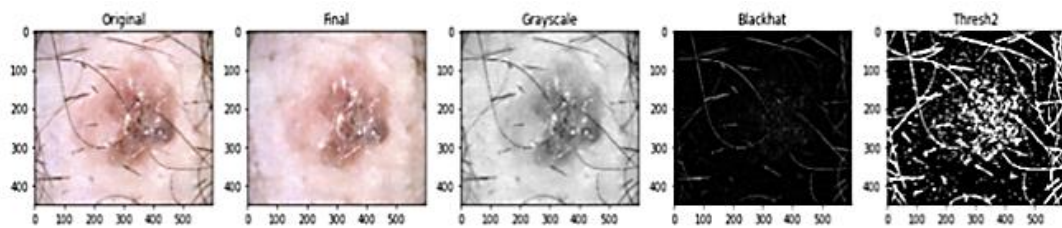


4
5 **Figure. 2** Proposed CNN for Dermoscopic Images Classification



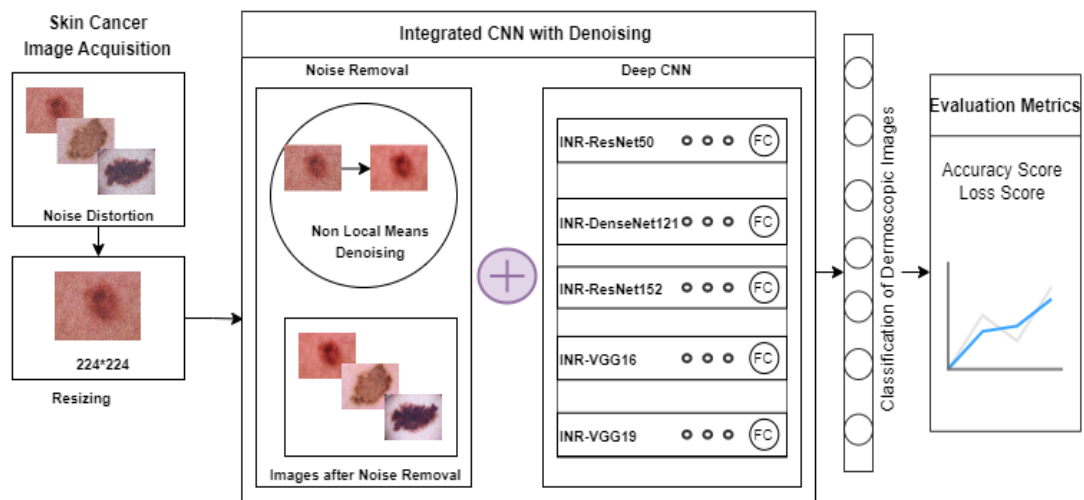
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2 **Figure. 3** Integration of CNN with Inpainting for Dermoscopic Hair Removal and
 3 **Classification**



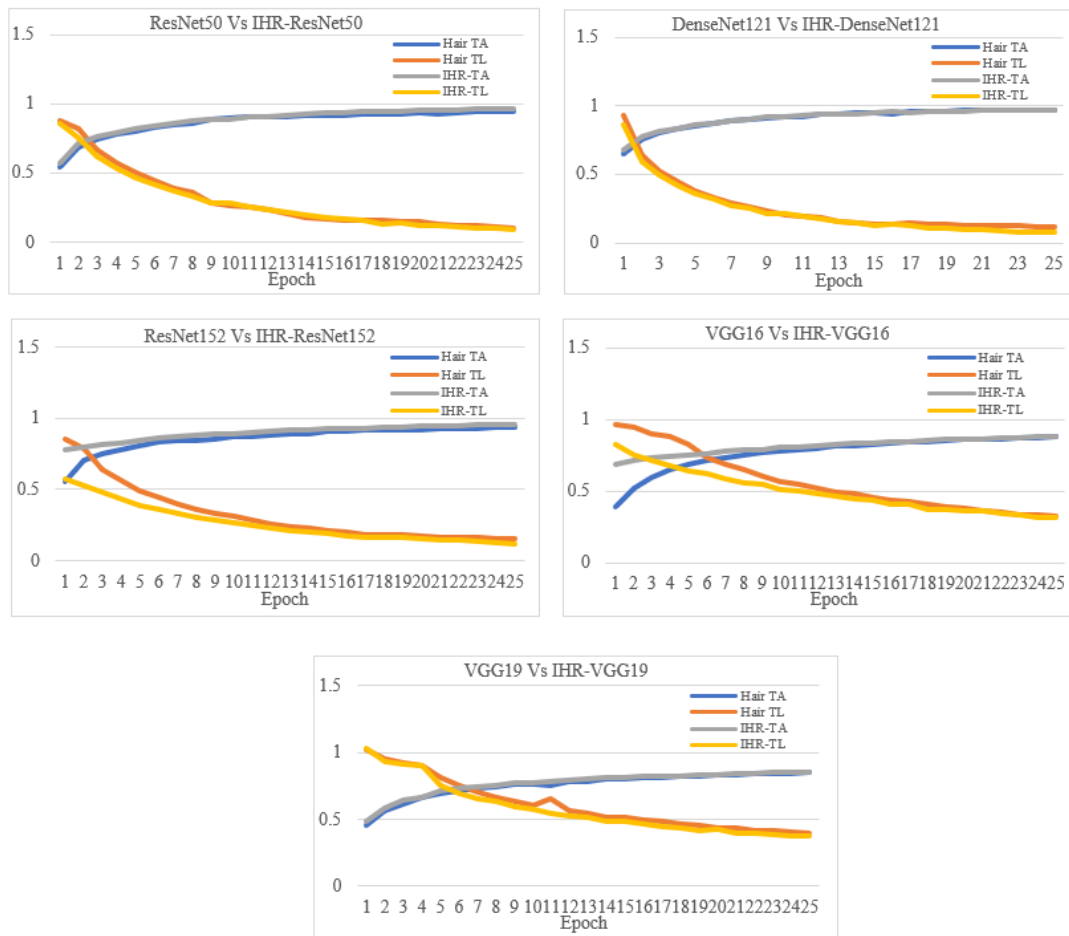
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5 **Figure. 4** Stages of the Hair removal process for Dermoscopic images



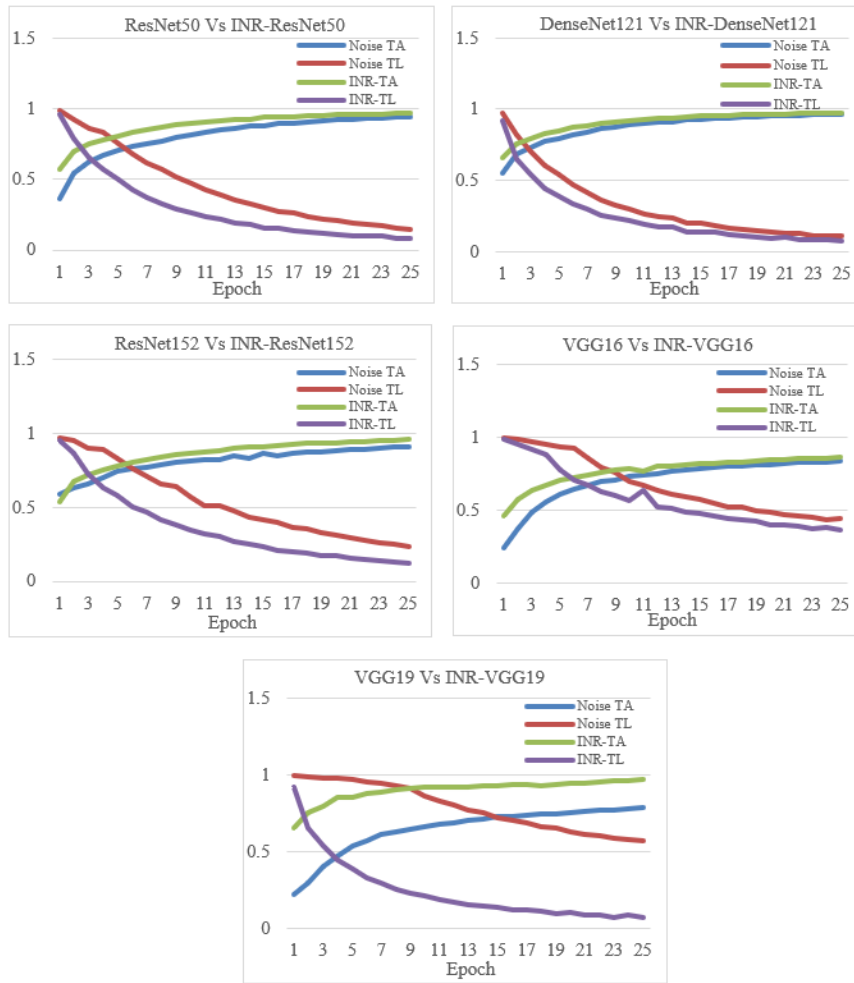
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7 **Figure. 5** Integration of CNN with Denoising for Dermoscopic Noise Removal and
 8 **Classification**



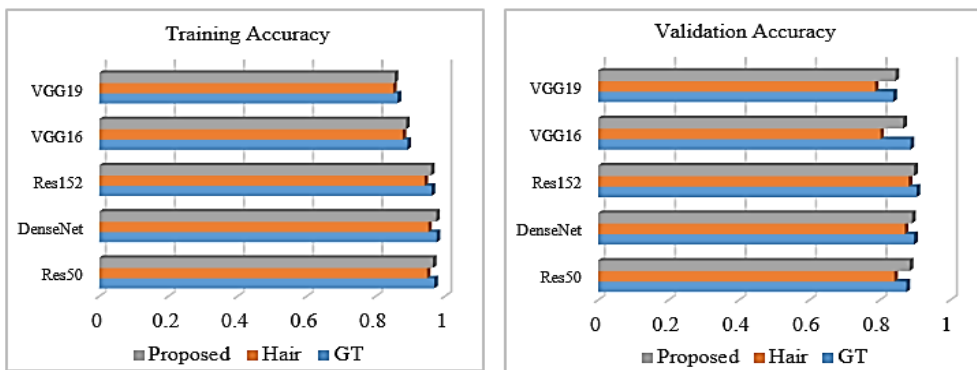
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2 **Figure. 6** Comparison of Improvement in Training Accuracy and Loss after Dehairing



1

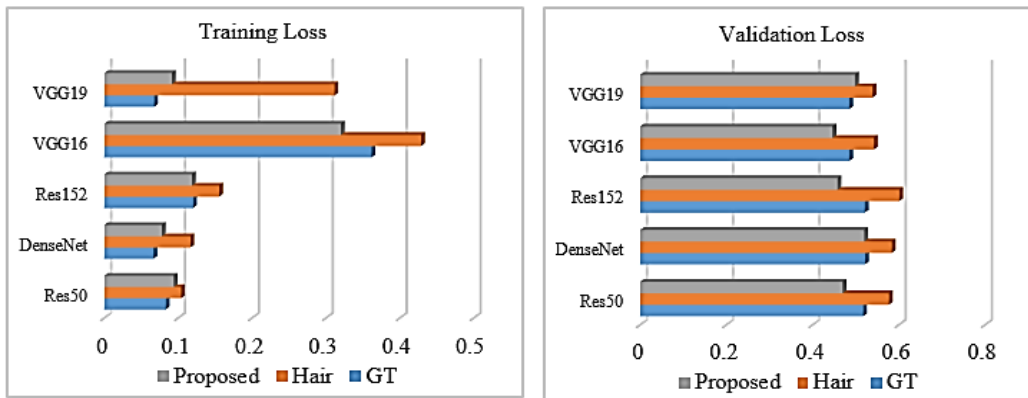
2 **Figure. 7** Comparison of Improvement in Training Accuracy and Loss after Denoising



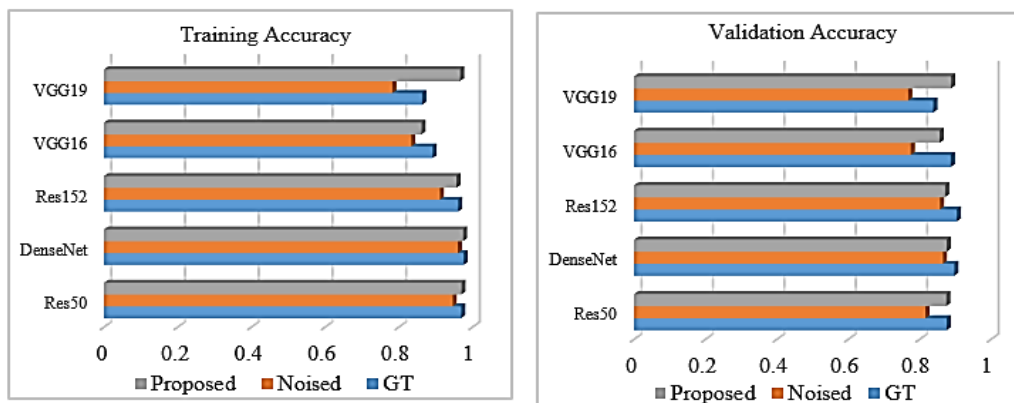
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4 **Figure. 8** Comparison of Improvement in Training and Validation Accuracy for GT,

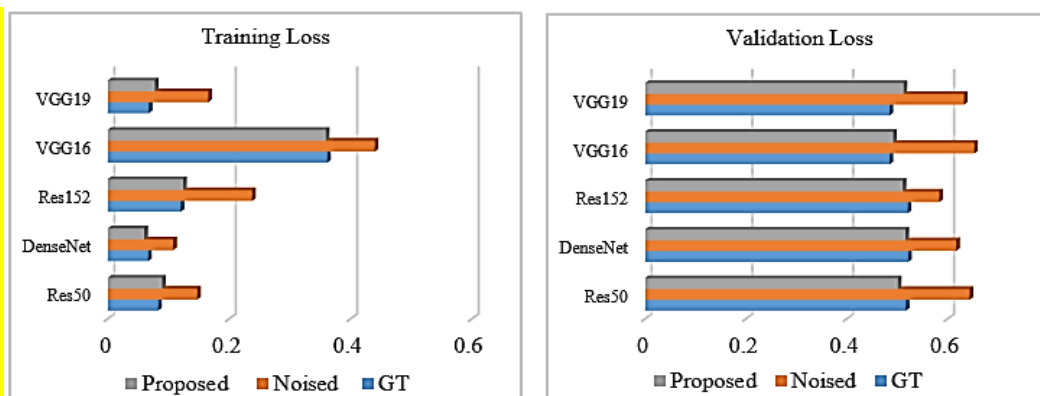
5 **Hair, and Proposed IHR Model**



1
2 **Figure. 9** Comparison of Improvement in Training and Validation Loss for GT, Hair,
3 and Proposed IHR Model



4
5 **Figure. 10** Comparison of Improvement in Training and Validation Accuracy for GT,
6 Noised, and Proposed INR Model



7
8 **Figure. 11** Comparison of Improvement in Training and Validation Loss for GT,
9 Noised and Proposed INR Model

1 **Table 1.** Number of Images per Category in the Dataset

Dataset	Description	No. of images opted for occlusion	No. of images for Classification
Dataset 1	Original Ground truth	-	10015
Dataset 2	Hair Strands	5000	10015
Dataset 3	Noise (Gaussian)	5000	10015

2

3 **Table 2.** Details of Deep Learning Architectures

Features	ResNet50	DenseNet121	ResNet152	VGG16	VGG19
No. of Layers	50	121	152	16	19
Top 5 Accuracy	0.921	0.923	0.931	0.901	0.900
No. of Parameters	25 million	8 million	60 million	138 million	143 million
Size	98 MB	33 MB	232 MB	528 MB	549 MB
Depth	168	121	-	23	26

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Table 3. Hyperparameters for the proposed work

S.No.	Name of Hyperparameter	Value of Hyperparameter
1.	Input Size	224 × 224 × 3
2.	Batch Size	32
3.	Epochs	25
4.	Optimization Function	ADAM
5.	Learning Rate	1e-3
6.	Loss function	Categorical Cross entropy
7.	Activation function	ReLU

Table 4. Training and Validation Accuracy on GT Dataset.

Epoch	ResNet50		DenseNet121		ResNet152		VGG16		VGG19	
	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc
10	0.902	0.840	0.938	0.870	0.892	0.859	0.813	0.821	0.782	0.812
7	7	7	2	1	1	5	2	0	7	9
15	0.941	0.880	0.956	0.897	0.925	0.900	0.852	0.860	0.823	0.816
4	4	3	9	0	5	4	0	3	0	6
25	0.969	0.875	0.976	0.897	0.961	0.904	0.891	0.887	0.863	0.838
4	4	6	3	2	4	3	8	2	4	0

1 **Table 5.** Training and Validation Loss on GT Dataset

Epoch	ResNet50		DenseNet121		ResNet152		VGG16		VGG19	
	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss
10	0.2631	0.4683	0.1663	0.4030	0.3471	0.4254	0.5697	0.5685	0.2079	0.5010
15	0.159	0.4446	0.1167	0.5547	0.2351	0.5132	0.4771	0.4619	0.1345	0.4619
25	0.0832	0.5175	0.0665	0.5219	0.1202	0.5213	0.3617	0.4852	0.0675	0.4852

2

3 **Table 6.** Training and Validation Accuracy on Hair Dataset

Epoch	ResNet50		DenseNet121		ResNet152		VGG16		VGG19	
	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc
10	0.9001	0.7932	0.9131	0.8283	0.8688	0.8423	0.7811	0.7731	0.7693	0.7273
15	0.9264	0.8129	0.9398	0.8447	0.9096	0.8752	0.8275	0.7922	0.8053	0.7710
25	0.9478	0.8411	0.9520	0.8710	0.9412	0.8819	0.8780	0.8018	0.8503	0.7862

4

1 **Table 7. Training and Validation Loss on Hair Dataset**

Epoch	ResNet50		DenseNet121		ResNet152		VGG16		VGG19	
	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss
10	0.2609	0.4465	0.204	0.4081	0.3087	0.4290	0.5705	0.5050	0.6049	0.5174
15	0.1688	0.4651	0.1352	0.5044	0.2144	0.4828	0.4538	0.4505	0.513	0.5715
25	0.1038	0.5772	0.1165	0.5837	0.1553	0.6012	0.4287	0.5424	0.3114	0.5390

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4 **Table 8. Training and Validation Accuracy after Dehairing on Hair Dataset**

Epoch	IHR-ResNet50		IHR-DenseNet121		IHR-ResNet152		IHR-VGG16		IHR-VGG19	
	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc
10	0.8918	0.8506	0.9184	0.8556	0.8949	0.8481	0.8134	0.7814	0.7754	0.8534
15	0.9327	0.8738	0.9506	0.8836	0.9288	0.8524	0.8549	0.8179	0.8142	0.8229
25	0.9656	0.8847	0.9750	0.8916	0.9601	0.89	0.8879	0.8663	0.8546	0.8445

1 **Table 9.** Training and Validation Loss after Dehairing on Hair Dataset

Epoch	IHR-ResNet50		IHR-DenseNet121		IHR-ResNet152		IHR-VGG16		IHR-VGG19	
	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss
10	0.2819	0.4567	0.2122	0.3898	0.2701	0.4991	0.5144	0.5511	0.2788	0.4354
15	0.1810	0.4651	0.1318	0.4114	0.1890	0.4860	0.4332	0.5582	0.1861	0.4567
25	0.0938	0.4696	0.0779	0.5198	0.1187	0.4581	0.3202	0.4461	0.0914	0.4985

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3 **Table 10.** Training and Validation Accuracy on Noise Dataset

Epoch	ResNet50		DenseNet121		ResNet152		VGG16		VGG19	
	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc	TAcc	VAcc
10	0.8179	0.7791	0.8871	0.8265	0.8120	0.7712	0.7322	0.7873	0.6642	0.7738
15	0.8821	0.8284	0.9275	0.8623	0.8658	0.8200	0.7848	0.7747	0.7251	0.7694
25	0.9462	0.8158	0.9604	0.8650	0.9114	0.8570	0.8339	0.7748	0.7825	0.7675

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1 **Table 11.** Training and Validation Loss on Noise Dataset

Epo c	ResNet50		DenseNet121		ResNet152		VGG16		VGG19	
	T L o s	V L o s	T L o s	V L o s	T L o s	V L o s	T L o s	V L o s	T L o s	V L o s
10	0.472 3	0.615 6	0.297 5	0.524 3	0.566 9	0.492 5	0.701 2	0.587 6	0.261 3	0.562 7
15	0.303 8	0.572 5	0.194 9	0.510 4	0.414 4	0.559 8	0.570 9	0.605 8	0.217 1	0.609 6
25	0.147 5	0.643 9	0.107 8	0.617 3	0.237 8	0.583 5	0.439 8	0.653 2	0.165 6	0.632 8

2

3 **Table 12.** Training and Validation Accuracy after Denoising on Noise Dataset

Epo c	INR- ResNet50		INR- DenseNet121		INR- ResNet152		INR-VGG16		INR-VGG19	
	T A c c	V A c c	T A c c	V A c c	T A c c	V A c c	T A c c	V A c c	T A c c	V A c c
10	0.898 2	0.852 5	0.917 9	0.888 3	0.867 2	0.847 0	0.782 4	0.774 4	0.919 4	0.869 5
15	0.940 4	0.871 3	0.950 5	0.845 3	0.908 0	0.842 5	0.816 9	0.837 3	0.927 2	0.873 1
25	0.970 1	0.874 7	0.974 5	0.875 8	0.956 5	0.871 0	0.861 7	0.856 0	0.966 5	0.888 2

4

1 **Table 13.** Training and Validation Loss after Denoising on Noise Dataset

Epoch	INR-ResNet50		INR-DenseNet121		INR-ResNet152		INR-VGG16		INR-VGG19	
	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss	TLoss	VLoss
10	0.2631	0.4683	0.2178	0.4030	0.3471	0.4254	0.5697	0.5685	0.2079	0.5010
15	0.159	0.4446	0.1338	0.5547	0.2351	0.5332	0.4771	0.4619	0.1345	0.5318
25	0.0895	0.5015	0.0602	0.5167	0.1242	0.5113	0.3592	0.4922	0.0775	0.5130

2

3 **Table 14.** Comparison with Existing Hair Removal Methods

Year	Method Used	Accuracy with Hair	Accuracy Post Hair
		Occlusion	Removal
(1997) [10]	DullRazor	-	93.15
(2011) [46]	PDE	-	91.74
(2013) [47]	Curvilinear Matched Filtering	-	81.13
(2013) [48]	Derivative of Gaussians	-	87.36
(2015) [49]	Threshold Decomposition	-	80.13
(2017) [50]	ED+MBL	-	90.99

(2021) [51]	SharpRazor	-	93.80
Proposed	Inpainting + DenseNet121	95.2	97.50
	Inpainting + ResNet50	94.78	96.56
INR	Inpainting + ResNet152	94.12	96.01

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2 **Table 15.** Comparison with Existing Noise Removal Methods

Year	Method Used	Accuracy with Noise Occlusion	Accuracy Post Noise Removal
(2016) [52]	UNet	-	87.25
(2021) [53]	DP-LinkNet	-	94.86
Proposed	Non-Local Means +DenseNet121	96.04	97.45
INR	Non-Local Means + ResNet 50	94.62	97.01
	Non-Local Means + VGG19	78.25	96.65

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